
statOT

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STATOT PACKAGE

1.1 Core implementation

`statot.inference.compute_conditional_mfpt` ($P, j, \text{sink_idx}$)

Compute conditional mean first passage time MFPT($x_i \rightarrow x_j$). Based on implementation in PBA.

Parameters

- P – transition matrix
- j – index j of cell x_j
- **sink_idx** – boolean array of length N , set to *True* for sinks and *False* otherwise.

Returns vector t_i containing MFPT($x_i \rightarrow x_j$)

`statot.inference.compute_fate_probs` ($P, \text{sink_idx}$)

Compute fate probabilities by individual sink cell

Parameters

- P – transition matrix
- **sink_idx** – boolean array of length N , set to *True* for sinks and *False* otherwise.

Returns matrix with dimensions (N, S) where S is the number of sink cells present.

`statot.inference.compute_fate_probs_lineages` ($P, \text{sink_idx}, \text{labels}$)

Compute fate probabilities by lineage

Parameters

- P – transition matrix
- **sink_idx** – boolean array of length N , set to *True* for sinks and *False* otherwise.
- **labels** – string array of length N containing lineage names. Only those entries corresponding to sinks will be used.

Returns matrix with dimensions (N, L) where L is the number of lineages with sinks.

`statot.inference.gaussian_tr` (C, h)

Form Gaussian (discrete heat flow) transition matrix of bandwidth h

Parameters

- C – pairwise square distances
- h – bandwidth

`statot.inference.row_normalise` ($\gamma, \text{sink_idx}=None$)

Enforce sink condition and row normalise coupling to produce transition matrix

Parameters

- **gamma** – coupling produced by *statot()*;
- **sink_idx** – boolean array of length N , set to *True* for sinks and *False* otherwise. If provided, sets the transition distributions for all sinks to be the identity.

Returns transition matrix obtained by row-normalising the input *gamma*.

```
statot.inference.statot(x, C=None, eps=None, method='ent', g=None, dt=None, maxiter=5000,  
                        tol=1e-09, verbose=False)
```

Fit statOT model

Parameters

- **x** – input data – N points of M dimensions in the form of a matrix with dimensions (N, M)
- **C** – cost matrix for optimal transport problem
- **eps** – regularisation parameter
- **method** – choice of regularisation – either “ent” (entropy) or “quad” (L2). “unbal” for unbalanced transport is not yet implemented. if “marginals”, return just *mu* and *nu*.
- **g** – numeric array of length N , containing the relative growth rates for cells.
- **flow_rate** – used only in the growth-free case (flow only)
- **dt** – choice of the time step over which to fit the model
- **maxiter** – max number of iterations for OT solver
- **tol** – relative tolerance for OT solver convergence
- **verbose** – detailed output on convergence of OT solver.

Returns gamma (optimal transport coupling), mu (source measure), nu (target measure)

```
statot.inference.velocity_from_transition_matrix(P, x, deltat)
```

Estimate velocity field from transition matrix (i.e. compute expected displacements)

Parameters

- **P** – transition matrix
- **x** – input data – N points of M dimensions in the form of a matrix with dimensions (N, M)
- **deltat** – timestep for which *P* was calculated.

1.2 CellRank wrapper

```
class statot.cr.OTKernel(adata, g, compute_cond_num=False)
```

Bases: `cellrank.tl.kernels._base_kernel.Kernel`

Kernel class allowing statOT method to be used from CellRank. Call first *set_terminal_states* to specify which cells to use as sinks.

Parameters

- **adata** – *AnnData* object containing N cells. We can use any embedding for statOT, selected when calling *OTKernel.compute_transition_matrix()*.
- **g** – string specifying the key in *adata.obs* to a numeric array of length N , containing the relative growth rates for cells, or the array itself.

- **compute_cond_num** – set to *True* to compute the condition number of the transition matrix.

compute_transition_matrix(*eps*, *dt*, *expr_key*='X_pca', *cost_norm_method*=None, *method*='ent', *tol*=1e-09, *thresh*=0, *maxiter*=5000, *C*=None, *verbose*=False)

Compute transition matrix using StationaryOT.

Parameters

- **eps** – regularisation parameter
- **dt** – choice of the time step over which to fit the model
- **expr_key** – key to embedding to use in *adata.obsm*.
- **cost_norm_method** – cost normalisation method to use. use “mean” to ensure $\text{mean}(C) = 1$, or refer to *ot.utils.cost_normalization* in Python OT.
- **thresh** – threshold for output transition probabilities (no thresholding by default)
- **maxiter** – max number of iterations for OT solver
- **C** – cost matrix for optimal transport problem
- **verbose** – detailed output on convergence of OT solver.

copy() → *statot.cr.OTKernel*

Return a copy of itself. Note that the underlying **:paramref:`adata`** object is not copied.

statot.cr.set_terminal_states(*adata*, *sink_idx*, *labels*, *terminal_colors*)

Set user-specified terminal states for CellRank API functions and OTKernel.

Parameters

- **adata** – *AnnData* object containing *N* cells.
- **sink_idx** – string specifying the key in *adata.uns* to a boolean array of length *N*, set to *True* for sinks and *False* otherwise, or the array itself.
- **labels** – string array of length *N* containing lineage names. Only those entries corresponding to sinks will be used.
- **terminal_colors** – colors corresponding to terminal state labels.

1.3 pyKeOps-numpy implementation

statot.keops.compute_fate_probs(*Q*, *R*)

Compute fate probabilities from *Q* (LazyTensor) and *R* (np.ndarray)

Parameters

- **Q** – transient part of transition matrix from *get_QR_submat*, as *LazyTensor*
- **R** – absorbing part of transition matrix. Should aggregate the columns across fates, since the solver cannot solve multiple RHS at once.

statot.keops.form_cost(*mu_spt*, *nu_spt*, *norm_factor*=None, *keops*=True)

Form cost matrix (matrix of squared Euclidean distances)

Parameters

- **mu_spt** – support of source measure

- **nu_spt** – support of target measure
- **norm_factor** – normalisation factor as a *float*, *None* or “mean”
- **keops** – whether to return a *LazyTensor* or *np.array*

`statot.keops.get_QR_submat_ent(u, K, v, X, sink_idx, eps, cost_norm_factor)`

Compute Q (as *LazyTensor*) and R (as *np.ndarray*) matrices for entropy-regularised OT dual potentials (u, v)

Parameters

- **u** – dual potential for source distribution
- **K** – Gibbs kernel as *LazyTensor*
- **v** – dual potential for target distribution
- **X** – coordinates as *np.ndarray*
- **sink_idx** – boolean array of length *N*, set to *True* for sinks and *False* otherwise.
- **eps** – value of *eps* used for solving with *sinkhorn*
- **cost_norm_factor** – normalisation factor used in *form_cost*

`statot.keops.get_QR_submat_quad(u, C, v, X, sink_idx, eps, cost_norm_factor)`

Compute Q (as *LazyTensor*) and R (as *np.ndarray*) matrices for quadratically regularised OT dual potentials (u, v)

Parameters

- **u** – dual potential for source distribution
- **C** – cost matrix as *LazyTensor*
- **v** – dual potential for target distribution
- **X** – coordinates as *np.ndarray*
- **sink_idx** – boolean array of length *N*, set to *True* for sinks and *False* otherwise.
- **eps** – value of *eps* used for solving with *quad_ot_semismooth_newton*
- **cost_norm_factor** – normalisation factor used in *form_cost*

`statot.keops.quad_ot_semismooth_newton(mu, nu, C, eps, max_iter=50, theta=0.1, kappa=0.5, tol=0.001, eta=1e-05, cg_max_iter=500, verbose=False)`

Semismooth Newton algorithm for solving quadratically regularised optimal transport compatible with KeOps *LazyTensor* framework. Uses the method from Algorithm 2 of Lorenz, D.A., Manns, P. and Meyer, C., 2019. *Quadratically regularized optimal transport. Applied Mathematics & Optimization, pp.1-31.*

Parameters

- **mu** – source distribution
- **nu** – target distribution
- **C** – cost matrix as *LazyTensor*
- **max_iter** – maximum number of Newton steps
- **theta** – Armijo control parameter (choose in (0, 1))

- **kappa** – Armijo step scaling parameter (choose in $(0, 1)$)
- **tol** – tolerance (inf-norm on marginals)
- **eta** – conjugate gradient regularisation parameter
- **cg_max_iter** – maximum number of conjugate gradient iterations
- **verbose** – flag for verbose output

`statot.keops.set_dtype(d)`
Set dtype to use in `statot.keops`

`statot.keops.sinkhorn(mu, nu, K, max_iter=5000, err_check=10, tol=1e-09, verbose=False)`

Sinkhorn algorithm for solving entropy-regularised optimal transport compatible with KeOps LazyTensor framework.

Parameters

- **mu** – source distribution
- **nu** – target distribution
- **K** – Gibbs kernel as *LazyTensor*
- **max_iter** – maximum number of iterations
- **err_check** – interval for checking marginal error
- **tol** – tolerance (inf-norm on marginals)
- **verbose** – flag for verbose output

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